## Ing. Květoslav Belda, Ph.D.

### **EDUCATION**

2006	Ph.D Dissertation: Control of Parallel Robotic Structures Driven by Electromotors
2002-	Second postgraduate education:
2005	Academy of Sciences of the Czech Republic (AS CR),
	Institute of Information Theory and Automation (UTIA),
	Department of Adaptive Systems;
	The Czech Technical University in Prague (CTU),
	Faculty of Electrical Engineering (FEE),
	Department of Mechanics and Materials; Faculty of Mechanical Engineering (FME),
	Department of Mechanics, Division of Mechanics of Bodies
	Theme: Control of Robotic Systems Driven by Electromotors
2003	<b>Ph.D Dissertation</b> : Control of Redundant Parallel Structures of Robotic Systems.
1999-	Postgraduate education:
2002	Academy of Sciences of the Czech Republic (AS CR),
2002	Institute of Information Theory and Automation (UTIA),
	Department of Adaptive Systems;
	The Czech Technical University in Prague (CTU),
	Faculty of Mechanical Engineering (FME),
	Department of Instrumentation and Control Engineering,
	Division of Automatic Control and Engineering Informatics;
	Department of Mechanics, Division of Mechanics of Bodies
	Theme: Control of Systems with More Inputs than Outputs
1999	Ing. (M.Sc.) - Diploma work: Cautions Strategy in LQ Adaptive Controllers
1994-	Undergraduate education:
1999	The Czech Technical University in Prague (CTU),
	Faculty of Mechanical Engineering (FME),
	Department of Instrumentation and Control Engineering,
	Division of Automatic Control and Engineering Informatics
1994	School-leaving exam
	(distinction; subjects: Mathematics, Czech, Engineering Technology, Operation and
4000	Structure of Machines)
1990-	High technical school BETLÉMSKÁ (Betlémská, Praha 1)
1994	

#### **PROFESSION**

**Professional** Model-based Control Design, Parallel Robotic Structures for Machine Tools,

**interests:** Industrial Robotics.

1999-now Researcher

Academy of Sciences of the Czech Republic (AS CR), Institute of Information Theory and Automation (UTIA),

Department of Adaptive Systems

**Teaching activities:** At Czech Technical University in Prague, Faculties <u>FEE</u> and <u>FME</u>. and at The College of Polytechnics Jihlava <u>CPJ</u>.

Proposals for possible semestral projects, theses, dissertations: click here!

#### List of the activities:

**2021-** Mechatronic Systems and Robotics (CPJ)

**2018-** Basics of Mechatronics (CPJ)

2018-2021 Basics of Robotics (CPJ)

2007-2008 Technical Documentation (FEE)

2006 Robots in Practice (FEE)

2002-2004 Technical Documentation (FEE)

**2000-2002** Mechanics - Statics, Kinematics and Dynamics (FME)

1999-2000 Computer Use Fundamentals (FME)

# **PROJECTS**

2006-2008	Model-based Control of Mechatronic Systems for Robotics (GA ČR 102/06/P275) project leader: K. Belda
2005-2007	Methods of Predictive Control, Algorithms and Implementation (GA ČR 102/05/0271) project leader: J. Böhm
2004	Implementation of Control in Redundant Parallel Robotic Structures (CTU IG 0406413)
2003-2005	Redundant Drives and Measurement for Hybrid Machine Tools (GAČR 101/03/0620) project leaders: M. Valášek, J. Böhm
2002	The Study of Properties of Independent (Decentralized) and Centralized Control of Redundant Parallel Robots (CTU IG 0204512)
2001 1999- 2001	The Direct Kinematics for Parallel Robots (CTU IG 300104412) Redundant Parallel Robots and Their Control (GAČR 101/99/0729) project leaders: M. Valášek, J. Böhm